

ROTARY PART HANDLER

Product Overview

INDEXERS

Servo Positioners



GTB Series
Globoidal (Roller Gear)
Servo Positioner.....IN-SRV-1



RSD Series
Rotary Servo Drives.....IN-SRV-39

Mechanical Indexers



RDM Series
Rotary Index Drive IN-MCH-2



RD Series
Roller Dial Index Drive..... IN-MCH-18



E Series
Heavy-Duty Index Drive IN-MCH-30



RA Series
Right Angle Index Drive IN-MCH-42



RGD/RGS Series
Roller Gear Index Drive IN-MCH-52



P Series
Parallel Shaft/Flange Drive.... IN-MCH-72



RNG Series
Ring Drive Dial Indexer.....IN-MCH-84

OVERLOAD CLUTCHES



Overload Clutches
Output Overload..... IN-CLU-1

CUSTOM CAMS



Custom Cams
Cam Design Solutions IN-CAM-1

CONVEYORS



Rite-Link Series
Thin-Profile.....IN-CNV-1



Precision Link Series
Table-TopIN-CNV-4



Precision Link Series
Heavy-Duty IN-CNV-16

PARTS HANDLERS



LPP Series
Linear Part Handlers IN-PRT-2



RPP Series
Rotary Part Handlers IN-PRT-8

ROTARY PART HANDLER

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Features:

The **CAMCO RPP Cambot® Rotary Parts Handler** is designed for high precision and high capacity. This proven design can be used in a wide variety of industries including automotive, packaging and electronics among others. The RPP can be combined with other CAMCO products such as index drives and precision conveyors for a complete, automated system. The RPP is ideal for pick and place applications with features including:

Rugged and precise cam operated mechanisms engineered for a minimum of 8000 hours of maintenance-free life.

Hardened and ground cams drive both the lift and rotary axes.

Preloaded precision cam followers eliminate backlash and ensure smooth movement.

Preloaded taper roller bearings on the camshaft (Input Shaft).

Four-point contact preloaded roller bearing on the rotary axis.

All bearings are lubricated by an oil bath.

One-piece lift arm.

Ball bushings (recirculating-ball type) support the main lift shaft and turn the large output surface and ride on hardened shafts for stability and stiffness.

Manufactured in a fully integrated application, design, manufacturing and inspection environment.

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ROTARY PART HANDLER

How to Order

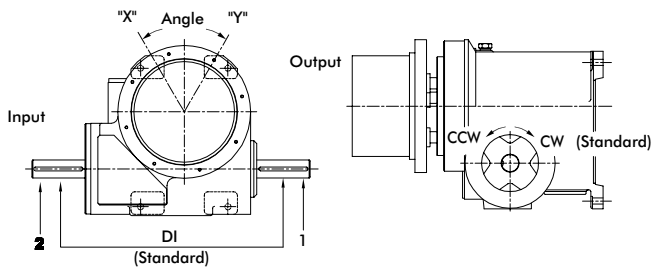
RPP Ordering Procedure

1. Model
2. Rotary Motion (degrees)
 - Oscillator or indexer
 - Oscillator: Home at X or Y
 - Indexer: CW or CCW index
3. Lift (inches)
4. Input Shaft: Side 1, Side 2 or Double Input (DI)
5. Mounting Position: 1-6

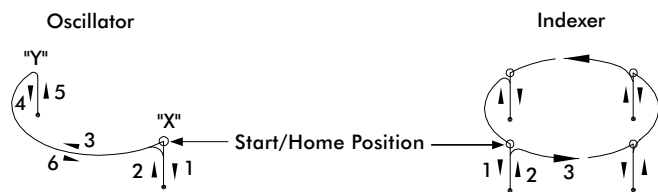
Reducer Ordering Procedure

1. Reducer Model, Ratio and Mounting Position
2. Motor Adaptor Model
3. Motor size

Input Shaft Configuration

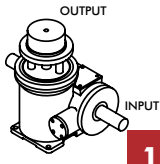
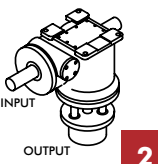
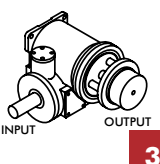
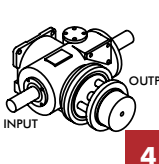
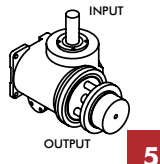
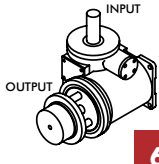


Standard Output Sequence

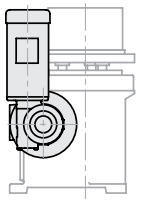
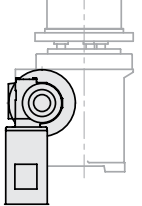
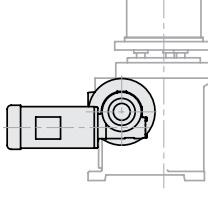
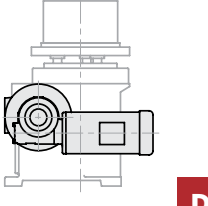
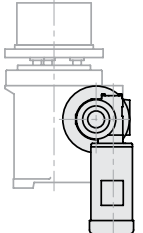
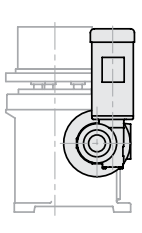
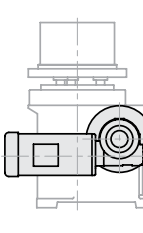
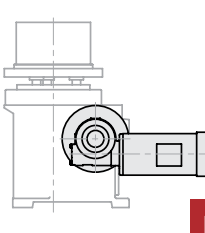
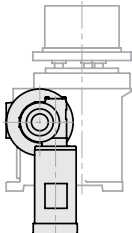
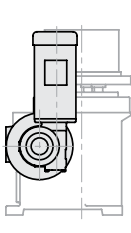
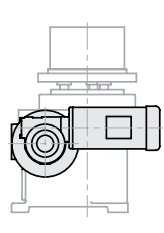
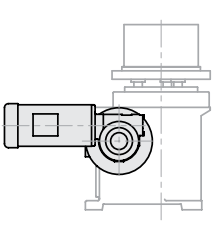
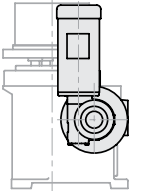
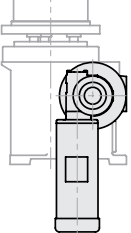
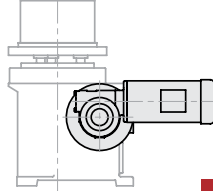
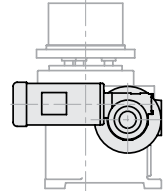


ROTARY PART HANDLER

Mounting Position

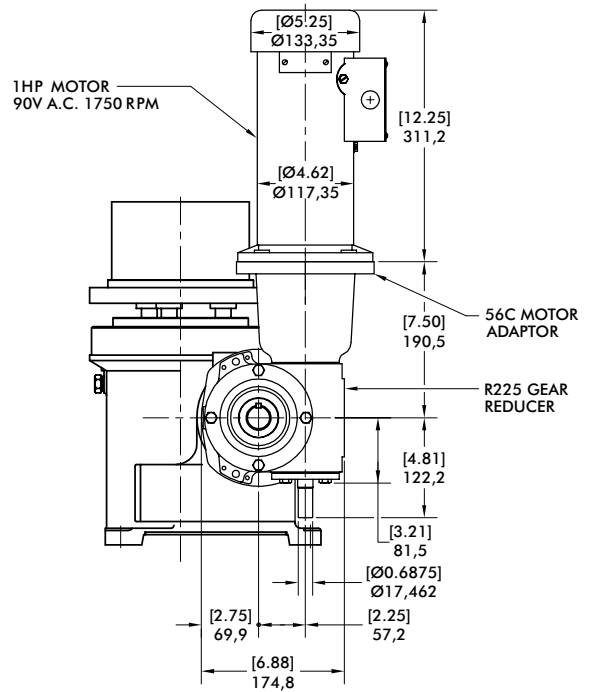
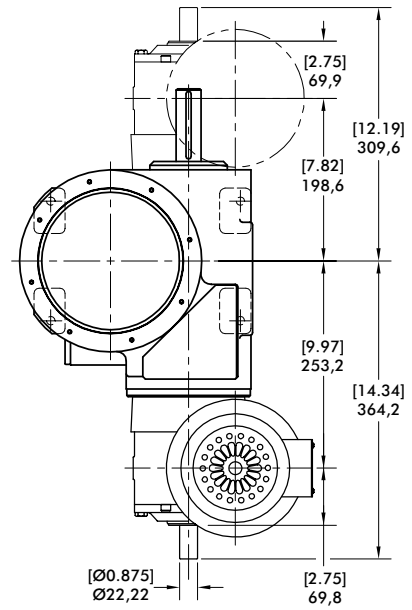
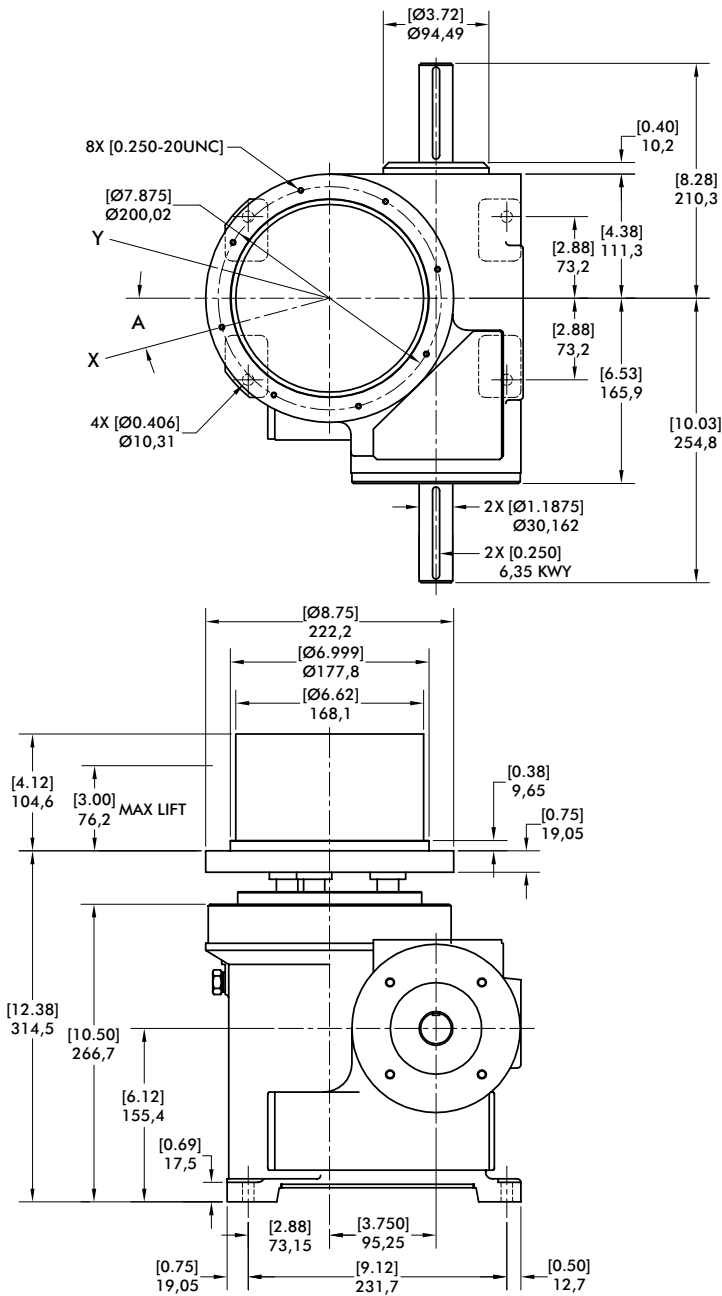
OVOI (output vertical, over input)	OVUI (output vertical, under input)	OHOI (output horizontal, over input)	OHUI (output horizontal, under input)	H-S1-UP (output horizontal, side 1 up)	H-S2-UP (output horizontal, side 2 up)
 1	 2	 3	 4	 5	 6

Gear Reducer Mounting Positions

		Mounting "A"		Mounting "B"	
		RH	LH	RH	LH
SIDE 1	 A	 B	 C	 D	
	SIDE 2	 E	 F	 G	 H
		Mounting "C"		Mounting "D"	
		RH	LH	RH	LH
SIDE 1	 J	 K	 L	 M	
	SIDE 2	 N	 P	 R	 S

300RPP SERIES

Rotary Part Handler | Configurations



Indexing Motion			
Rotation	Angle A	Lift mm [in]	Model
120°	0°	25,4 [1]	300RPP120H24-1H24
		50,8 [2]	300RPP120H24-2H24
90°	15°	25,4 [1]	300RPP90H24-1H24
		50,8 [2]	300RPP90H24-2H24
		76,2 [3]	300RPP90H24-3H24
60°	0°	25,4 [1]	300RPP60H24-1H24
		50,8 [2]	300RPP60H24-2H24
		76,2 [3]	300RPP60H24-3H24
45°	22.5°	25,4 [1]	300RPP45H24-1H24
		50,8 [2]	300RPP45H24-2H24
		76,2 [3]	300RPP45H24-3H24

Oscillating Motion			
Rotation	Angle A	Lift mm [in]	Model
180°	0°	25,4 [1]	300RPP2H24-1H24
		50,8 [2]	300RPP2H24-2H24
		76,2 [3]	300RPP2H24-3H24
120°	0°	25,4 [1]	300RPP3H24-1H24
		50,8 [2]	300RPP3H24-2H24
		76,2 [3]	300RPP3H24-3H24
90°	0°	25,4 [1]	300RPP4H24-1H24
		50,8 [2]	300RPP4H24-2H24
		76,2 [3]	300RPP4H24-3H24
60°	0°	25,4 [1]	300RPP6H24-1H24
		50,8 [2]	300RPP6H24-2H24

Features

- Standard Indexing or Oscillating Motion
- R225 Reducer (Ratios from 5:1 to 60:1)
— 56C Motor Adapter and Coupling
- 1 HP AC Drive Package with Inverter Duty Motor and Inverter Drive (up to 60 cpm)

Optional Accessories

- 1 HP DC Motor
- Varipak DC Motor Control (up to 30 cpm)

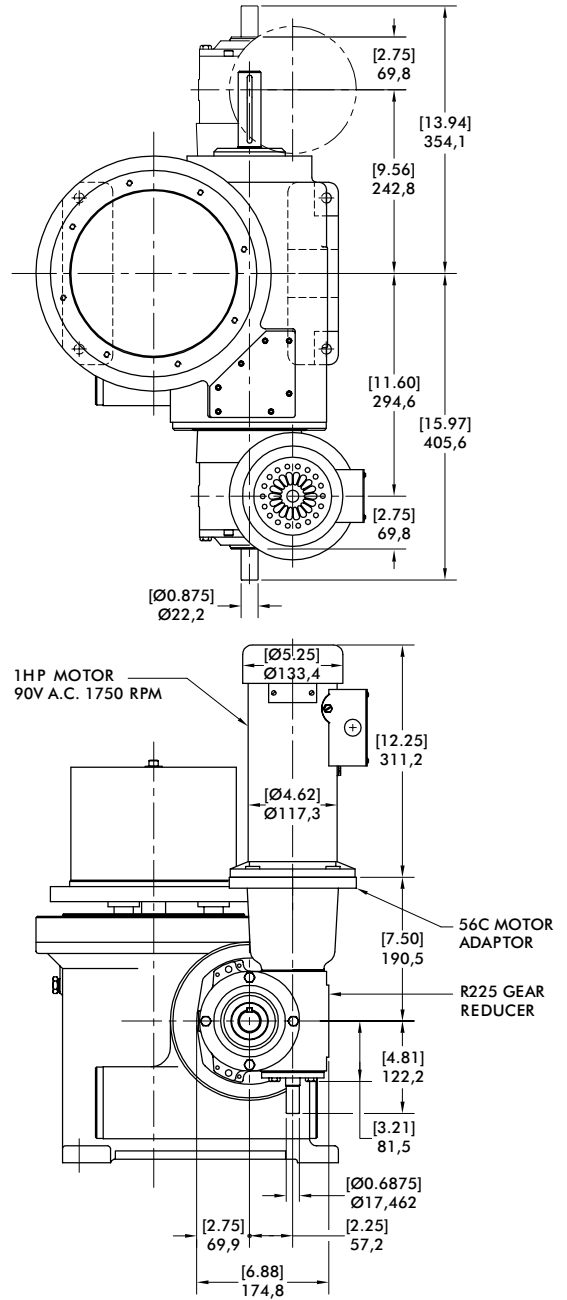
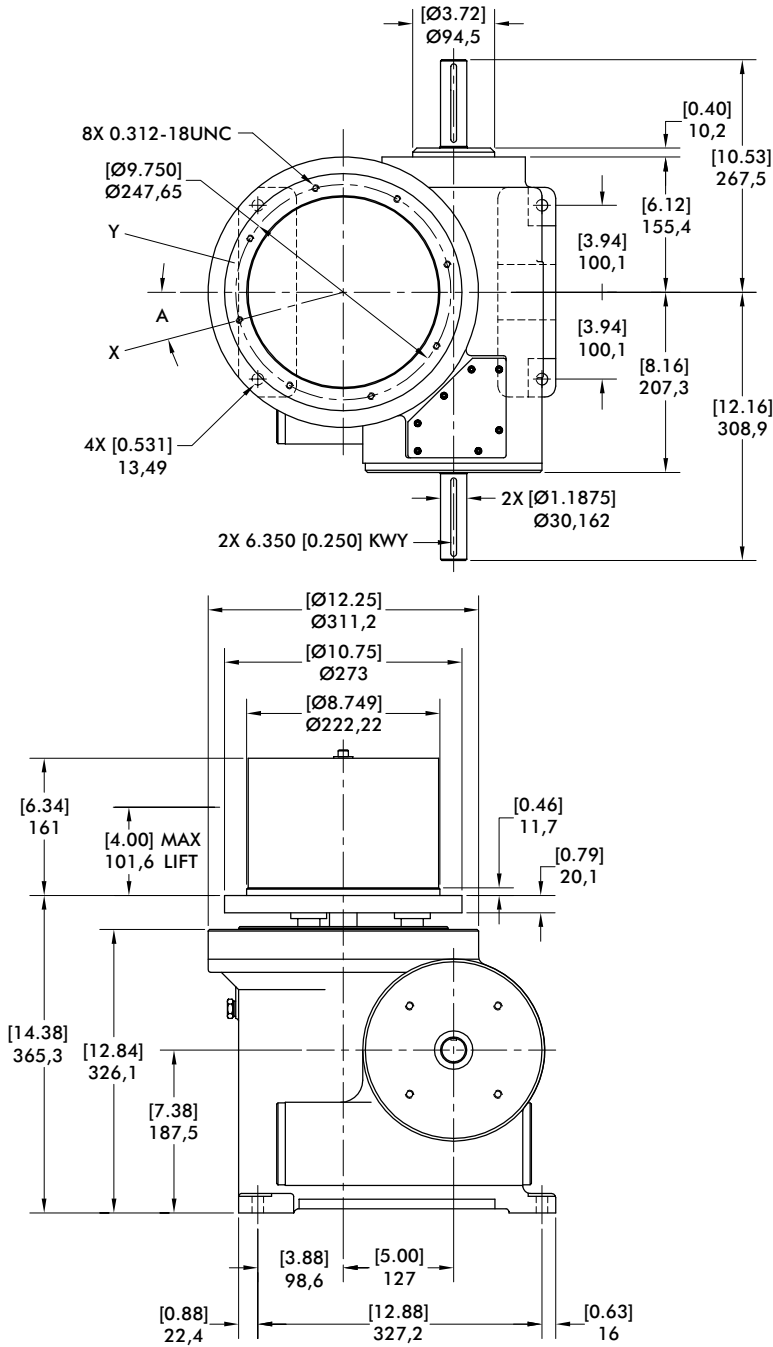
Capacity:*

Maximum Mass	68,04 kg [150 lbm]
Maximum Inertia	4975 kg-cm ² [1700 lb-in ²]

* Note: These values are for speeds of less than 30 rpm, the minimum cam time for rise and rotation, and are for reference only. Each application must be reviewed and approved by CAMCO Engineering.

500RPP SERIES

Rotary Part Handler | Configurations



Indexing Motion			
Rotation	Angle A	Lift mm [in]	Model
180°	0°	50,8 [2]	500RPP2H32-2H32
		76,2 [3]	500RPP2H32-3H32
		101,6 [4]	500RPP2H32-4H32
120°	0°	50,8 [2]	500RPP3H32-2H32
		76,2 [3]	500RPP3H32-3H32
		101,6 [4]	500RPP3H32-4H32
90°	0°	50,8 [2]	500RPP4H32-2H32
		76,2 [3]	500RPP4H32-3H32
		101,6 [4]	500RPP4H32-4H32
60°	0°	50,8 [2]	500RPP6H32-2H32
		76,2 [3]	500RPP6H32-3H32
		101,6 [4]	500RPP6H32-4H32

Oscillating Motion			
Rotation	Angle A	Lift mm [in]	Model
120°	0°	50,8 [2]	500RPP120H32-2H32
		76,2 [3]	500RPP120H32-3H32
90°	15°	50,8 [2]	500RPP90H32-2H32
		76,2 [3]	500RPP90H32-3H32
		101,6 [4]	500RPP90H32-4H32
60°	0°	50,8 [2]	500RPP60H32-2H32
		76,2 [3]	500RPP60H32-3H32
		101,6 [4]	500RPP60H32-4H32
45°	22.5°	50,8 [2]	500RPP45H32-2H32
		76,2 [3]	500RPP45H32-3H32
		101,6 [4]	500RPP45H32-4H32

Features

- Standard Indexing or Oscillating Motion
- R225 Reducer (Ratios from 5:1 to 60:1)
— 56C Motor Adapter and Coupling
- 1 hp AC Drive Package with Inverter Duty Motor and Inverter Drive (up to 60 cpm)

Optional Accessories

- 1 hp DC Motor
- Varipak DC Motor Control (up to 30 cpm)

Capacity:*

Maximum Mass	81,65 kg [180 lbm]
Maximum Inertia	9204 kg-cm ² [3145 lb-in ²]

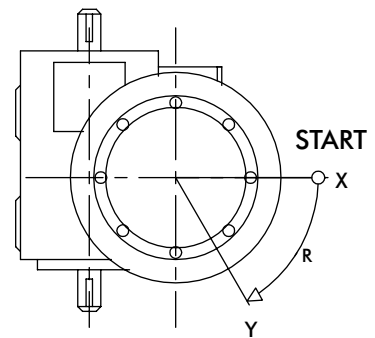
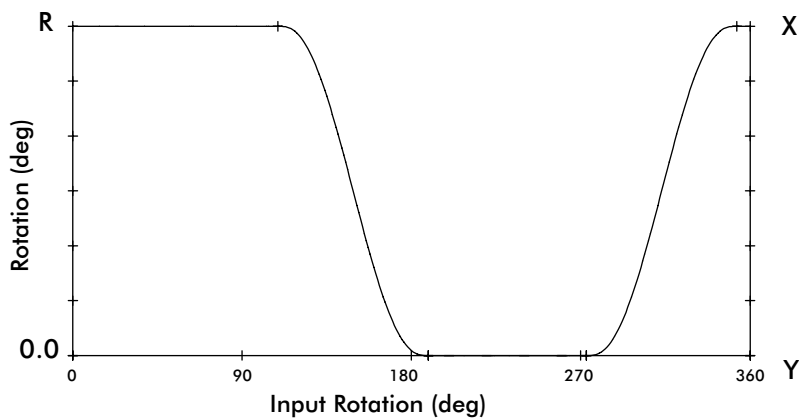
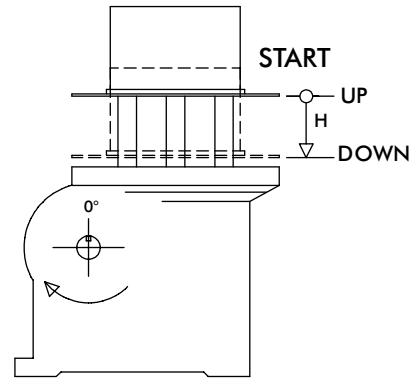
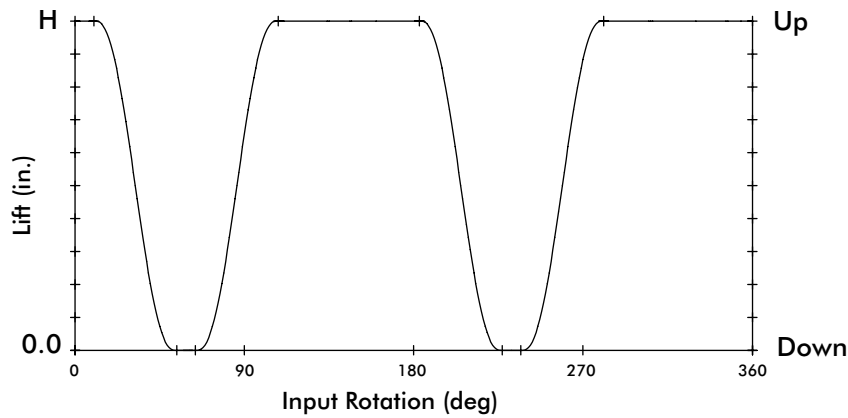
Capacity:*

Maximum Mass	180 lbs
Maximum Inertia	3415 lb-in ²

* Note: These values are for speeds of less than 30 rpm, the minimum cam time for rise and rotation, and are for reference only. Each application must be reviewed and approved by CAMCO Engineering.

ROTARY PART HANDLER

Oscillator Timing Diagram

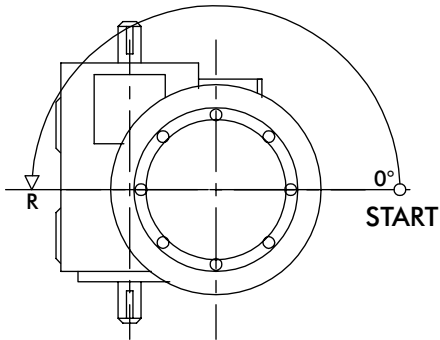
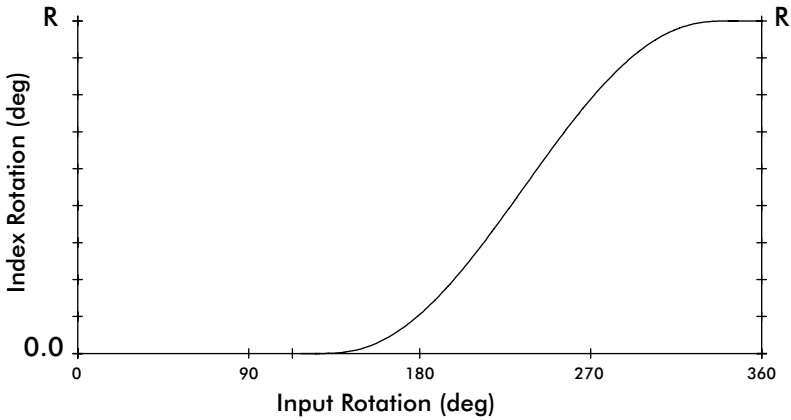
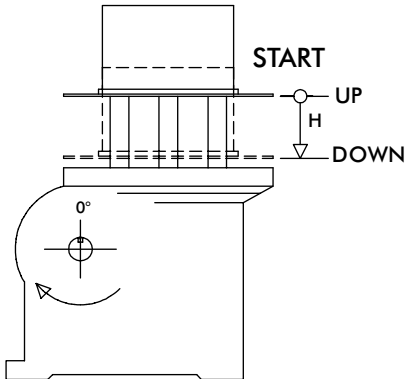
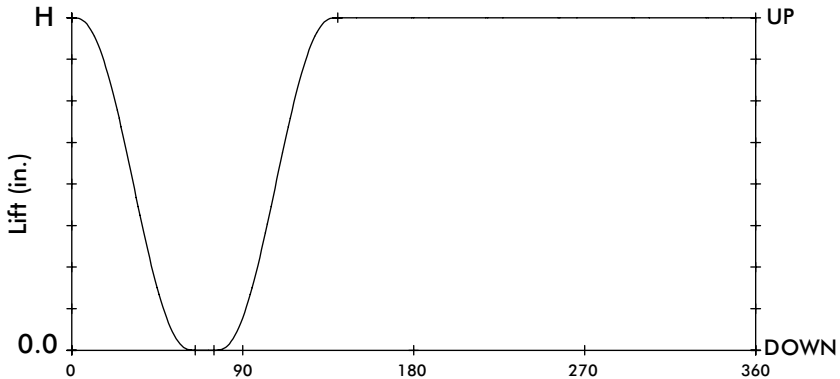


Motion Options

- Standard starting position (home) at time 0 is at maximum rise (up) and at the X rotary position.
- The standard sequence can be mirrored in either the lift, rotary or both:
 - The mirrored lift starts in the zero elevation or down position
 - The mirrored rotary motion starts at Y.
- Custom motion times are also available – consult your Sales Agent for more information.

ROTARY PART HANDLER

Indexer Timing Diagram



Motion Options

- Standard starting position (home) at time 0 is at maximum rise (up) and at the start of a counter-clockwise index (right-hand cam helix).
- The standard sequence can be mirrored in either the lift, rotary or both:
 - The mirrored lift starts in the zero elevation or down position
 - The mirrored rotary motion is a clockwise index (left-hand helix)
- Custom motion times are also available – consult your Sales Agent for more information.